# Abstract 3-Rigidity and Bivariate Splines 

Bill Jackson<br>School of Mathematical Sciences<br>Queen Mary, University of London<br>England

Circle Packings and Geometric Rigidity ICERM July 6-10, 2020

## Matroids

A matroid $\mathcal{M}$ is a pair $(E, \mathcal{I})$ where $E$ is a finite set and $\mathcal{I}$ is a family of subsets of $E$ satisfying:

- $\emptyset \in \mathcal{I}$;
- if $B \in \mathcal{I}$ and $A \subseteq B$ then $A \in \mathcal{I}$;
- if $A, B \in \mathcal{I}$ and $|A|<|B|$ then there exists $x \in B \backslash A$ such that $A+x \in \mathcal{I}$.


## Matroids

A matroid $\mathcal{M}$ is a pair $(E, \mathcal{I})$ where $E$ is a finite set and $\mathcal{I}$ is a family of subsets of $E$ satisfying:

- $\emptyset \in \mathcal{I}$;
- if $B \in \mathcal{I}$ and $A \subseteq B$ then $A \in \mathcal{I}$;
- if $A, B \in \mathcal{I}$ and $|A|<|B|$ then there exists $x \in B \backslash A$ such that $A+x \in \mathcal{I}$.
$A \subseteq E$ is independent if $A \in \mathcal{I}$ and $A$ is dependent if $A \notin \mathcal{I}$. The minimal dependent sets of $\mathcal{M}$ are the circuits of $\mathcal{M}$. The rank of $A, r(A)$, is the cardinality of a maximal independent subset of $A$. The rank of $\mathcal{M}$ is the cardinality of a maximal independent subset of $E$.


## Matroids

A matroid $\mathcal{M}$ is a pair $(E, \mathcal{I})$ where $E$ is a finite set and $\mathcal{I}$ is a family of subsets of $E$ satisfying:

- $\emptyset \in \mathcal{I}$;
- if $B \in \mathcal{I}$ and $A \subseteq B$ then $A \in \mathcal{I}$;
- if $A, B \in \mathcal{I}$ and $|A|<|B|$ then there exists $x \in B \backslash A$ such that $A+x \in \mathcal{I}$.
$A \subseteq E$ is independent if $A \in \mathcal{I}$ and $A$ is dependent if $A \notin \mathcal{I}$. The minimal dependent sets of $\mathcal{M}$ are the circuits of $\mathcal{M}$. The rank of $A, r(A)$, is the cardinality of a maximal independent subset of $A$. The rank of $\mathcal{M}$ is the cardinality of a maximal independent subset of $E$.

The weak order on a set $S$ of matroids with the same groundset is defined as follows. Given two matroids $\mathcal{M}_{1}=\left(E, \mathcal{I}_{1}\right)$ and $M_{2}=\left(E, \mathcal{I}_{2}\right)$ in $S$, we say $\mathcal{M}_{1} \preceq M_{2}$ if $\mathcal{I}_{1} \subseteq \mathcal{I}_{2}$.

The generic $d$-dimensional rigidity matroid

A d-dimensional framework $(G, p)$ is a graph $G=(V, E)$ together with a map $p: V \rightarrow \mathbb{R}^{d}$.

A d-dimensional framework $(G, p)$ is a graph $G=(V, E)$ together with a map $p: V \rightarrow \mathbb{R}^{d}$.
The rigidity matrix of $(G, p)$ is the matrix $R(G, p)$ of size
$|E| \times d|V|$ in which the row associated with the edge $v_{i} v_{j}$ is

$$
v_{i} v_{j}\left[\begin{array}{llllll}
0 \ldots 0 & p\left(v_{i}\right)^{v_{i}}-p\left(v_{j}\right) & 0 \ldots 0 & p\left(v_{j}\right)^{v_{j}}-p\left(v_{i}\right) & 0 \ldots 0
\end{array}\right] .
$$

A dimensional framework $(G, p)$ is a graph $G=(V, E)$ together with a map $p: V \rightarrow \mathbb{R}^{d}$.
The rigidity matrix of $(G, p)$ is the matrix $R(G, p)$ of size $|E| \times d|V|$ in which the row associated with the edge $v_{i} v_{j}$ is

$$
v_{i} v_{j}\left[\begin{array}{llllll}
0 \ldots 0 & p\left(v_{i}\right)^{v_{i}}-p\left(v_{j}\right) & 0 \ldots 0 & p\left(v_{j}\right)-p\left(v_{i}\right) & 0 \ldots 0
\end{array}\right]
$$

The generic $d$-dimensional rigidity matroid $\mathcal{R}_{n, d}$ is the row matroid of the rigidity matrix $R\left(K_{n}, p\right)$ for any generic $p: V\left(K_{n}\right) \rightarrow \mathbb{R}^{d}$.

## The generic $d$-dimensional rigidity matroid

A dimensional framework $(G, p)$ is a graph $G=(V, E)$ together with a map $p: V \rightarrow \mathbb{R}^{d}$.
The rigidity matrix of $(G, p)$ is the matrix $R(G, p)$ of size
$|E| \times d|V|$ in which the row associated with the edge $v_{i} v_{j}$ is

$$
v_{i} v_{j}\left[\begin{array}{lllll}
0 \ldots 0 & p\left(v_{i}\right)-p\left(v_{j}\right) & 0 \ldots 0 & p\left(v_{j}\right)-p\left(v_{i}\right) & 0 \ldots 0
\end{array}\right] .
$$

The generic $d$-dimensional rigidity matroid $\mathcal{R}_{n, d}$ is the row matroid of the rigidity matrix $R\left(K_{n}, p\right)$ for any generic $p: V\left(K_{n}\right) \rightarrow \mathbb{R}^{d}$.
$\mathcal{R}_{n, d}$ is a matroid with groundset $E\left(K_{n}\right)$ and rank $d n-\binom{d+1}{2}$. Its rank function has been determined (by good characterisations and polynomial algorithms) when $d=1,2$.
Determining its rank function for $d \geq 3$ is a long standing open problem.

## Abstract d-rigidity matroids

Jack Graver (1991) chose two closure properties of $\mathcal{R}_{d, n}$ and used them to define the family of abstract $d$-rigidity matroids on $E\left(K_{n}\right)$. Viet Hang Nguyen (2010) gave the following equivalent definition: $\mathcal{M}$ is an abstract $d$-rigidity matroid iff rank $\mathcal{M}=d n-\binom{d+1}{2}$, and every $K_{d+2} \subseteq K_{n}$ is a circuit in $\mathcal{M}$.

## Abstract d-rigidity matroids

Jack Graver (1991) chose two closure properties of $\mathcal{R}_{d, n}$ and used them to define the family of abstract $d$-rigidity matroids on $E\left(K_{n}\right)$. Viet Hang Nguyen (2010) gave the following equivalent definition: $\mathcal{M}$ is an abstract $d$-rigidity matroid iff rank $\mathcal{M}=d n-\binom{d+1}{2}$, and every $K_{d+2} \subseteq K_{n}$ is a circuit in $\mathcal{M}$.

## Conjecture [Graver, 1991]

For all $d, n \geq 1, \mathcal{R}_{d, n}$ is the unique maximal element in the family of all abstract $d$-rigidity matroids on $E\left(K_{n}\right)$.

## Abstract d-rigidity matroids

Jack Graver (1991) chose two closure properties of $\mathcal{R}_{d, n}$ and used them to define the family of abstract $d$-rigidity matroids on $E\left(K_{n}\right)$. Viet Hang Nguyen (2010) gave the following equivalent definition: $\mathcal{M}$ is an abstract $d$-rigidity matroid iff rank $\mathcal{M}=d n-\binom{d+1}{2}$, and every $K_{d+2} \subseteq K_{n}$ is a circuit in $\mathcal{M}$.

## Conjecture [Graver, 1991]

For all $d, n \geq 1, \mathcal{R}_{d, n}$ is the unique maximal element in the family of all abstract $d$-rigidity matroids on $E\left(K_{n}\right)$.

Graver verified his conjecture for $d=1,2$.

## Abstract d-rigidity matroids

Jack Graver (1991) chose two closure properties of $\mathcal{R}_{d, n}$ and used them to define the family of abstract $d$-rigidity matroids on $E\left(K_{n}\right)$. Viet Hang Nguyen (2010) gave the following equivalent definition: $\mathcal{M}$ is an abstract $d$-rigidity matroid iff rank $\mathcal{M}=d n-\binom{d+1}{2}$, and every $K_{d+2} \subseteq K_{n}$ is a circuit in $\mathcal{M}$.

## Conjecture [Graver, 1991]

For all $d, n \geq 1, \mathcal{R}_{d, n}$ is the unique maximal element in the family of all abstract $d$-rigidity matroids on $E\left(K_{n}\right)$.

Graver verified his conjecture for $d=1,2$.
Walter Whiteley (1996) gave counterexamples to Graver's conjecture for all $d \geq 4$ and $n \geq d+2$ using 'cofactor matroids'.

## Bivariate Splines and Cofactor Matrices

Given a polygonal subdivision $\Delta$ of a polygonal domain $D$ in the plane, a bivariate function $f: D \rightarrow \mathbb{R}$ is an $(s, k)$-spline over $\Delta$ if it is defined as a polynomial of degree $s$ on each face of $\Delta$ and is continuously differentiable $k$ times on $D$.

## Bivariate Splines and Cofactor Matrices

Given a polygonal subdivision $\Delta$ of a polygonal domain $D$ in the plane, a bivariate function $f: D \rightarrow \mathbb{R}$ is an $(s, k)$-spline over $\Delta$ if it is defined as a polynomial of degree $s$ on each face of $\Delta$ and is continuously differentiable $k$ times on $D$.

- The set $S_{s}^{k}(\Delta)$ of $(s, k)$-splines over $\Delta$ forms a vector space.
- Obtaining tight upper/lower bounds on $\operatorname{dim} S_{s}^{k}(\Delta)$ (over a given class of subdivisions $\Delta$ ) is an important problem in approximation theory.


## Bivariate Splines and Cofactor Matrices

Given a polygonal subdivision $\Delta$ of a polygonal domain $D$ in the plane, a bivariate function $f: D \rightarrow \mathbb{R}$ is an $(s, k)$-spline over $\Delta$ if it is defined as a polynomial of degree $s$ on each face of $\Delta$ and is continuously differentiable $k$ times on $D$.

- The set $S_{s}^{k}(\Delta)$ of $(s, k)$-splines over $\Delta$ forms a vector space.
- Obtaining tight upper/lower bounds on $\operatorname{dim} S_{s}^{k}(\Delta)$ (over a given class of subdivisions $\Delta$ ) is an important problem in approximation theory.
- Whiteley (1990) observed that $\operatorname{dim} S_{s}^{k}(\Delta)$ can be calculated from the rank of a matrix $C_{s}^{k}(G, p)$ which is determined by the the 1 -skeleton $(G, p)$ of the subdivision $\Delta$ (viewed as a 2-dim framework), and that rigidity theory can be used to investigate the rank of this matrix.
- His definition of $C_{s}^{k}(G, p)$ makes sense for all 2-dim frameworks (not just frameworks whose underlying graph is planar).


## Cofactor matroids

Let $(G, p)$ be a 2-dimensional framework and put $p\left(v_{i}\right)=\left(x_{i}, y_{i}\right)$ for $v_{i} \in V(G)$. For $v_{i} v_{j} \in E(G)$ and $d \geq 1$ let

$$
D_{d}\left(v_{i}, v_{j}\right)=\left(\left(x_{i}-x_{j}\right)^{d-1},\left(x_{i}-x_{j}\right)^{d-2}\left(y_{i}-y_{j}\right), \ldots,\left(y_{i}-y_{j}\right)^{d-1}\right)
$$

## Cofactor matroids

Let $(G, p)$ be a 2-dimensional framework and put $p\left(v_{i}\right)=\left(x_{i}, y_{i}\right)$ for $v_{i} \in V(G)$. For $v_{i} v_{j} \in E(G)$ and $d \geq 1$ let

$$
D_{d}\left(v_{i}, v_{j}\right)=\left(\left(x_{i}-x_{j}\right)^{d-1},\left(x_{i}-x_{j}\right)^{d-2}\left(y_{i}-y_{j}\right), \ldots,\left(y_{i}-y_{j}\right)^{d-1}\right)
$$

The $C_{d-1}^{d-2}$-cofactor matrix of $(G, p)$ is the matrix $C_{d-1}^{d-2}(G, p)$ of size $|E| \times d|V|$ in which the row associated $\underset{v_{i}}{\text { with }}$ the edge $v_{i} v_{j}$ is

$$
v_{i} v_{j}\left[\begin{array}{lllll}
0 \ldots 0 & D_{d}\left(v_{i}, v_{j}\right) & 0 \ldots 0 & -D_{d}\left(v_{i}, v_{j}\right) & 0 \ldots 0
\end{array}\right] .
$$

## Cofactor matroids

Let $(G, p)$ be a 2-dimensional framework and put $p\left(v_{i}\right)=\left(x_{i}, y_{i}\right)$ for $v_{i} \in V(G)$. For $v_{i} v_{j} \in E(G)$ and $d \geq 1$ let

$$
D_{d}\left(v_{i}, v_{j}\right)=\left(\left(x_{i}-x_{j}\right)^{d-1},\left(x_{i}-x_{j}\right)^{d-2}\left(y_{i}-y_{j}\right), \ldots,\left(y_{i}-y_{j}\right)^{d-1}\right) .
$$

The $C_{d-1}^{d-2}$-cofactor matrix of $(G, p)$ is the matrix $C_{d-1}^{d-2}(G, p)$ of size $|E| \times d|V|$ in which the row associated $\underset{v_{i}}{\text { with }}$ the edge $v_{i} v_{j}$ is

$$
v_{i} v_{j}\left[\begin{array}{llllll}
0 \ldots 0 & D_{d}\left(v_{i}, v_{j}\right) & 0 \ldots 0 & -D_{d}\left(v_{i}, v_{j}\right) & 0 \ldots 0
\end{array}\right] .
$$

The generic $C_{d-1}^{d-2}$-cofactor matroid, $\mathcal{C}_{d-1, n}^{d-2}$ is the row matroid of the cofactor matrix $C_{d-1}^{d-2}\left(K_{n}, p\right)$ for any generic $p: V\left(K_{n}\right) \rightarrow \mathbb{R}^{2}$.

## Cofactor matroids

Let $(G, p)$ be a 2-dimensional framework and put $p\left(v_{i}\right)=\left(x_{i}, y_{i}\right)$ for $v_{i} \in V(G)$. For $v_{i} v_{j} \in E(G)$ and $d \geq 1$ let

$$
D_{d}\left(v_{i}, v_{j}\right)=\left(\left(x_{i}-x_{j}\right)^{d-1},\left(x_{i}-x_{j}\right)^{d-2}\left(y_{i}-y_{j}\right), \ldots,\left(y_{i}-y_{j}\right)^{d-1}\right)
$$

The $C_{d-1}^{d-2}$-cofactor matrix of $(G, p)$ is the matrix $C_{d-1}^{d-2}(G, p)$ of size $|E| \times d|V|$ in which ${ }_{v_{i}}$, row associated $\underset{v_{j}}{\text { with }}$ the edge $v_{i} v_{j}$ is

$$
v_{i} v_{j}\left[\begin{array}{llllll}
0 \ldots 0 & D_{d}\left(v_{i}, v_{j}\right) & 0 \ldots 0 & -D_{d}\left(v_{i}, v_{j}\right) & 0 \ldots 0
\end{array}\right] .
$$

The generic $C_{d-1}^{d-2}$-cofactor matroid, $\mathcal{C}_{d-1, n}^{d-2}$ is the row matroid of the cofactor matrix $C_{d-1}^{d-2}\left(K_{n}, p\right)$ for any generic $p: V\left(K_{n}\right) \rightarrow \mathbb{R}^{2}$. $\mathcal{C}_{d-1, n}^{d-2}$ is a matroid with groundset $E\left(K_{n}\right)$ and rank $d n-\binom{d+1}{2}$.

## Cofactor matroids - Whiteley's Results and Conjectures

## Theorem [Whiteley]

- $\mathcal{C}_{d-1, n}^{d-2}$ is an abstract $d$-rigidity matroid for all $d, n \geq 1$.
- $\mathcal{C}_{d-1, n}^{d-2}=\mathcal{R}_{d, n}$ for $d=1,2$.
- $\mathcal{C}_{d-1, n}^{d-2} \npreceq \mathcal{R}_{d, n}$ when $d \geq 4$ and $n \geq 2(d+2)$ since $K_{d+2, d+2}$ is independent in $\mathcal{C}_{d-1, n}^{d-2}$ and dependent in $\mathcal{R}_{d, n}$.


## Cofactor matroids - Whiteley's Results and Conjectures

## Theorem [Whiteley]

- $\mathcal{C}_{d-1, n}^{d-2}$ is an abstract $d$-rigidity matroid for all $d, n \geq 1$.
- $\mathcal{C}_{d-1, n}^{d-2}=\mathcal{R}_{d, n}$ for $d=1,2$.
- $\mathcal{C}_{d-1, n}^{d-2} \npreceq \mathcal{R}_{d, n}$ when $d \geq 4$ and $n \geq 2(d+2)$ since $K_{d+2, d+2}$ is independent in $\mathcal{C}_{d-1, n}^{d-2}$ and dependent in $\mathcal{R}_{d, n}$.


## Conjecture [Whiteley, 1996]

For all $d, n \geq 1, \mathcal{C}_{d-1, n}^{d-2}$ is the unique maximal abstract $d$-rigidity matroid on $E\left(K_{n}\right)$.

## Cofactor matroids - Whiteley's Results and Conjectures

## Theorem [Whiteley]

- $\mathcal{C}_{d-1, n}^{d-2}$ is an abstract $d$-rigidity matroid for all $d, n \geq 1$.
- $\mathcal{C}_{d-1, n}^{d-2}=\mathcal{R}_{d, n}$ for $d=1,2$.
- $\mathcal{C}_{d-1, n}^{d-2} \npreceq \mathcal{R}_{d, n}$ when $d \geq 4$ and $n \geq 2(d+2)$ since $K_{d+2, d+2}$ is independent in $\mathcal{C}_{d-1, n}^{d-2}$ and dependent in $\mathcal{R}_{d, n}$.


## Conjecture [Whiteley, 1996]

For all $d, n \geq 1, \mathcal{C}_{d-1, n}^{d-2}$ is the unique maximal abstract $d$-rigidity matroid on $E\left(K_{n}\right)$.

Conjecture [Whiteley, 1996]
For all $n \geq 1, \mathcal{C}_{2, n}^{1}=\mathcal{R}_{3, n}$.

The maximal abstract 3-rigidity matroid
Theorem [Clinch, BJ, Tanigawa 2019+]
$\mathcal{C}_{2, n}^{1}$ is the unique maximal abstract 3 -rigidity matroid on $E\left(K_{n}\right)$.

## The maximal abstract 3-rigidity matroid

## Theorem [Clinch, BJ, Tanigawa 2019+]

$\mathcal{C}_{2, n}^{1}$ is the unique maximal abstract 3-rigidity matroid on $E\left(K_{n}\right)$.
Sketch Proof Suppose $\mathcal{M}$ is an abstract 3-rigidity matroid on $E\left(K_{n}\right)$ and $F \subseteq E\left(K_{n}\right)$ is independent in $M$. We show that $F$ is independent in $\mathcal{C}_{2, n}^{1}$ by induction on $|F|$. Since $\mathcal{M}$ is an abstract 3-rigidity matroid, $|F|=r(F) \leq 3|V(F)|-6$ and hence $F$ has a vertex $v$ with $d_{F}(v) \leq 5$.

## The maximal abstract 3-rigidity matroid

## Theorem [Clinch, BJ, Tanigawa 2019+]

$\mathcal{C}_{2, n}^{1}$ is the unique maximal abstract 3 -rigidity matroid on $E\left(K_{n}\right)$.
Sketch Proof Suppose $\mathcal{M}$ is an abstract 3-rigidity matroid on $E\left(K_{n}\right)$ and $F \subseteq E\left(K_{n}\right)$ is independent in $M$. We show that $F$ is independent in $\mathcal{C}_{2, n}^{1}$ by induction on $|F|$. Since $\mathcal{M}$ is an abstract 3-rigidity matroid, $|F|=r(F) \leq 3|V(F)|-6$ and hence $F$ has a vertex $v$ with $d_{F}(v) \leq 5$.

$$
\text { Case 1: } d_{F}(v) \leq 3
$$


independent in $\mathcal{M}$

$\xrightarrow{\text { axiom }}$

## The maximal abstract 3-rigidity matroid

## Theorem [Clinch, BJ, Tanigawa 2019+]

$\mathcal{C}_{3, n}^{2}$ is the unique maximal abstract $d$-rigidity matroid on $E\left(K_{n}\right)$.
Sketch Proof Suppose $\mathcal{M}$ is an abstract rigidity matroid on $E\left(K_{n}\right)$ and $F \subseteq E\left(K_{n}\right)$ is independent in $M$. We show that $F$ is independent in $\mathcal{C}_{2, n}^{1}$ by induction on $|F|$. Since $\mathcal{M}$ is an abstract 3-rigidity matroid, $|F|=r(F) \leq 3|V(F)|-6$ and hence $F$ has a vertex $v$ with $d_{F}(v) \leq 5$.

$$
\text { Case 2: } d_{F}(v)=4
$$


independent in $\mathcal{M}$

independent in $\mathcal{M}$
independent in $C_{2, n}^{1}$

independent in $C_{2, n}^{1}$

The maximal abstract 3-rigidity matroid
Case 3: $d_{F}(v)=5$


The rank function of $\mathcal{C}_{2, n}^{1}$

A $K_{5}$-sequence in $K_{n}$ is a sequence of subgraphs $\left(K_{5}^{1}, K_{5}^{2}, \ldots, K_{5}^{t}\right)$ each of which is isomorphic to $K_{5}$.
It is proper if $K_{5}^{i} \nsubseteq \bigcup_{j=1}^{i-1} K_{5}^{j}$ for all $2 \leq i \leq t$.

A $K_{5}$-sequence in $K_{n}$ is a sequence of subgraphs $\left(K_{5}^{1}, K_{5}^{2}, \ldots, K_{5}^{t}\right)$ each of which is isomorphic to $K_{5}$.
It is proper if $K_{5}^{i} \nsubseteq \bigcup_{j=1}^{i-1} K_{5}^{j}$ for all $2 \leq i \leq t$.

## Theorem [Clinch, BJ, Tanigawa 2019+]

The rank of any $F \subseteq E\left(K_{n}\right)$ in $\mathcal{C}_{2, n}^{1}$ is given by

$$
r(F)=\min \left\{\left|F_{0}\right|+\left|\bigcup_{i=1}^{t} E\left(K_{5}^{i}\right)\right|-t\right\}
$$

where the minimum is taken over all $F_{0} \subseteq F$ and all proper $K_{5}$-sequences $\left(K_{5}^{1}, K_{5}^{2}, \ldots, K_{5}^{t}\right)$ in $K_{n}$ which cover $F \backslash F_{0}$.

## Example



Let $F_{0}=\left\{e_{1}, e_{2}, e_{3}\right\}$ and $\left(K_{5}^{1}, K_{5}^{2}, \ldots, K_{5}^{7}\right)$ be the 'obvious' proper $K_{5}$-sequence which covers $F \backslash F_{0}$. We have $|F|=60$ and

$$
r(F) \leq\left|F_{0}\right|+\left|\bigcup_{i=1}^{7} E\left(K_{5}^{i}\right)\right|-7=59
$$

so $F$ is not independent in $\mathcal{C}_{2, n}^{1}$. Since $3|V(F)|-6=60, F$ is not rigid in any abstract 3-rigidity matroid.

## Application

## Theorem [Clinch, BJ, Tanigawa 2019+]

Every 12-connected graph is rigid in the maximal abstract 3 -rigidity matroid $C_{2, n}^{1}$.

## Application

## Theorem [Clinch, BJ, Tanigawa 2019+]

Every 12-connected graph is rigid in the maximal abstract 3-rigidity matroid $C_{2, n}^{1}$.

Lovász and Yemini (1982) conjectured that the analogous result holds for the generic 3-dimensional rigidity matroid. Examples constructed by Lovász and Yemini show that the connectivity hypothesis in the above theorem is best possible.

## Open Problems

> Problem 1 Determine whether the X-replacement operation preserves independence in the generic 3-dimensional rigidity matroid (Tay and Whiteley, 1985).

## Open Problems

Problem 1 Determine whether the X-replacement operation preserves independence in the generic 3-dimensional rigidity matroid (Tay and Whiteley, 1985).

Problem 2 Find a polynomial algorithm for determining the rank function of $\mathcal{C}_{2, n}^{1}$.

## Open Problems

Problem 1 Determine whether the X-replacement operation preserves independence in the generic 3-dimensional rigidity matroid (Tay and Whiteley, 1985).

Problem 2 Find a polynomial algorithm for determining the rank function of $\mathcal{C}_{2, n}^{1}$.
Problem 3 Determine whether the following function $\rho_{d}: 2^{E\left(K_{n}\right)} \rightarrow \mathbb{Z}$ is submodular.

$$
\rho_{d}(F)=\min \left\{\left|F_{0}\right|+\left|\bigcup_{i=1}^{t} E\left(K_{d+2}^{i}\right)\right|-t\right\}
$$

where the minimum is taken over all $F_{0} \subseteq F$ and all proper $K_{d+2}$-sequences $\left(K_{d+2}^{1}, K_{d+2}^{2}, \ldots, K_{d+2}^{t}\right)$ in $K_{n}$ which cover $F \backslash F_{0}$. An affirmative answer would tell us that there is a unique maximal abstract $d$-rigidity matroid and $\rho_{d}$ is its rank function.

## Preprints

K. Clinch, B. Jackson and S. Tanigawa, Abstract 3-rigidity and bivariate $C_{2}^{1}$-splines I: Whiteley's maximality conjecture, preprint available at https://arxiv.org/abs/1911. 00205.
K. Clinch, B. Jackson and S. Tanigawa, Abstract 3-rigidity and bivariate $C_{2}^{1}$-splines II: Combinatorial Characterization, preprint available at https://arxiv.org/abs/1911.00207.

